

# Future Networked Car Symposium

FNC2025



UNECE



## SESSION 2: Challenges in Achieving Effective Vehicle Remote Driving





# Mapless AI

Drive. Remotely. Safely.

# Leadership Team



**Philipp Robbel, PhD**

CEO and Co-Founder

- Director of Engineering at nuTonomy – led safety and simulation teams (acquired in 2017)
- Head of Safety at Aptiv Autonomous Mobility
- Engineering at Bosch (L4 Highway Pilot)
- PhD in Robotics, MIT



**Jeffrey Kane Johnson, PhD**

CTO and Co-Founder

- Technical expert in Autonomous Vehicle systems
- Built AV navigation at Bosch, Apple, and Uber
- Principal Investigator in NSF award for vehicle safety system
- Computer Science PhD, Indiana University



**BOSCH**



• **A P T I V** •

**Uber**

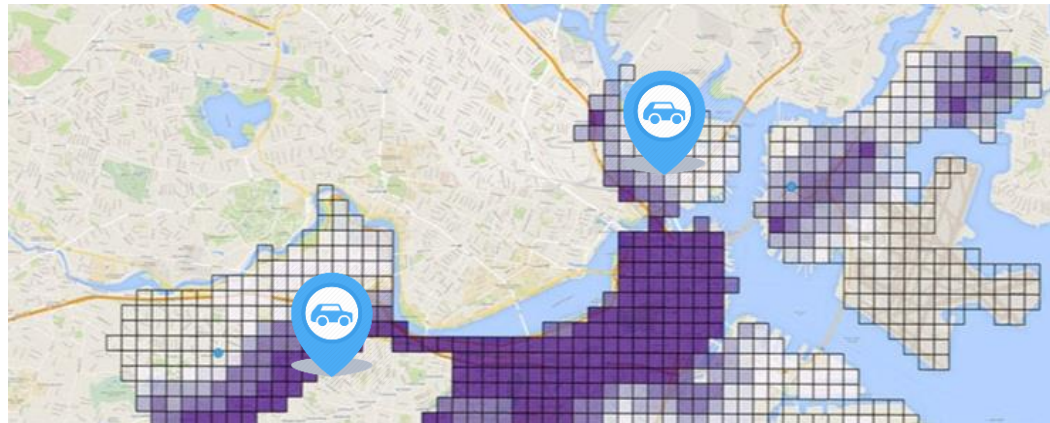


# Vehicle Movement is Critical for Fleet Operations



## Fleet side:

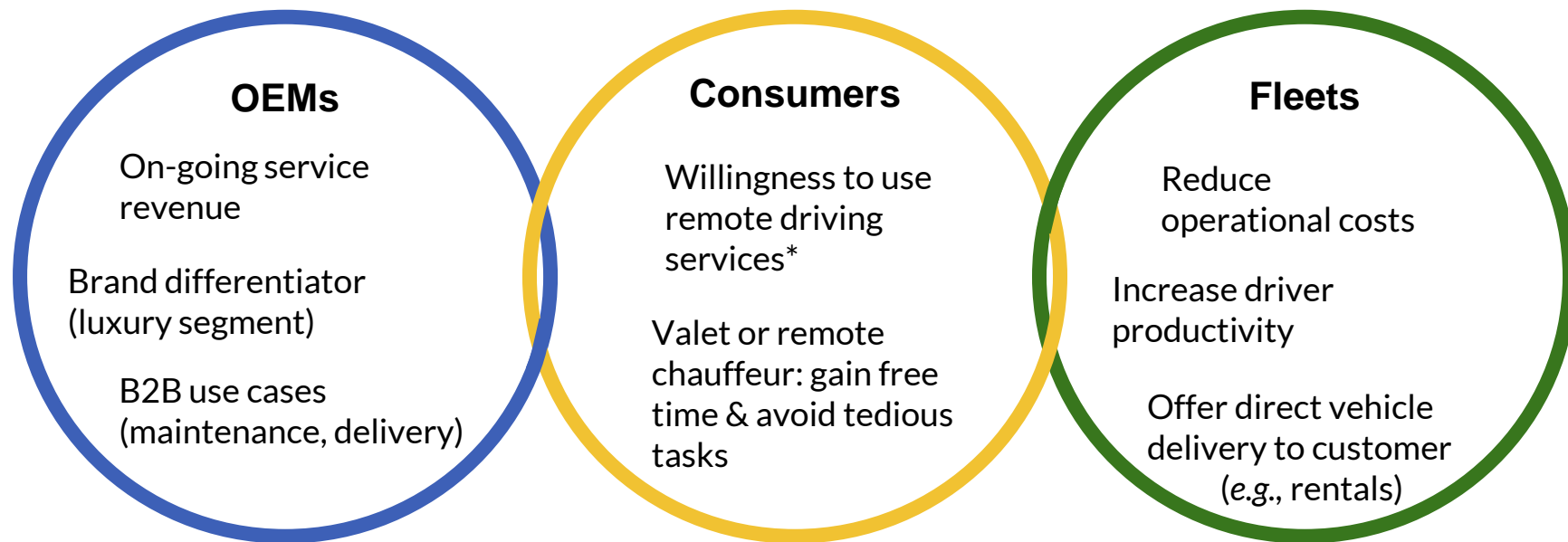
- Keep driver productivity high
- Rebalance fleet effectively



## Customer-facing side:

- Meet needs for vehicle availability
- Enable new revenue streams from use cases like vehicle delivery on demand

# Benefits to Remote Driving



\* McKinsey & Co, "Remote-driving services: The next disruption in mobility innovation?" (Jan 3, 2025)

# Mapless AI: Full Stack for Public Road Operation



- Optimized install targeting fleet partners
- Trained remote driver staff
- Targeted to automotive standards
- Safe motion at all times - independent of network

# Ensuring Safe Motion during Remote Driving

## Full Safety concept for remote driving

- Supports remote driving or AV stack
- Automotive-grade
- ADAS-level pricing

## Redundant Sensors

- Cameras and LIDAR—processed locally on vehicle
- Forward sensor cleaning



Low-latency perception and control contingency layer is required for mitigating safety hazards during Teleoperation.

## Cellular bonding < 6Ghz

- Redundant 4G/5G Sub-6 channels
- Link management: load balancing, FEC

## Safety System

- Redundant safety (2x brake)
- Backup power
- Fully-driverless operation

# Deployments





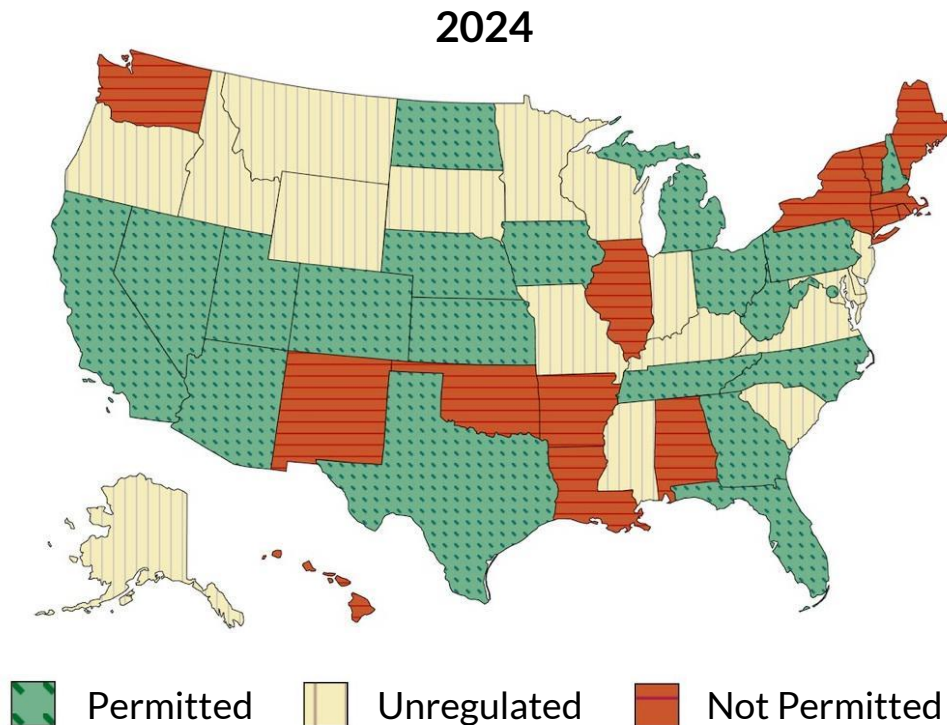
# Areas of Operation

## Mapless operation:

- Pittsburgh, PIT airport, Harrisburg, PA
- Detroit, MI
- Tampa, FL
- Massachusetts

## Use cases:

- Carshare
- Fleet Ops
- Vehicle manufacturing



# Corktown Carshare

Corktown Carshare is available in the Detroit Corktown area since Feb, 2025

Remote driving unlocks *virtual parking spots* and return to charging hub.



# Corktown Carshare



**Vehicles are controlled from control center in Pittsburgh, PA.**



Transportation Innovation Zone  
Detroit, MI

M  
SH  
RC  
SF

23 mph D

# #ConnectedCar

## Discussion Topics



# Topics of Interest @ Mapless

- **Application layer tooling**
  - Effects of package drop / latency / jitter \*)
  - Fault injection testing
- **Operator longitudinal motion perception**
  - HUD overlays, sound
- **Reaction to link degradation**
  - Corrective measures (bandwidth adjustment)
- **Prediction of link performance**
  - Offline: mapping
  - Online: RB allocation
- **Safety system**
  - Conservative, safe actions in times of degraded performance



\*) *Not just a teleoperation issue! Cf. NHTSA AV STEP comments (2025)*

# Move Vehicles Without Moving People



VIP invites for  
rides in Detroit,  
Pittsburgh, or  
Boston:

[vip@mapless.ai](mailto:vip@mapless.ai)