




Artificial General Intelligence and Automated Vehicles: An Answer to Safe Mobility?

Bryan Reimer, Ph.D. | MIT Center for Transportation & Logistics AgeLab
Future Networked Car Symposium (FNC-2022) | March 23rd, 2022

Roadway Safety is a Global, Under-Treated Public Health Crisis



Over
1.25M
fatalities a year



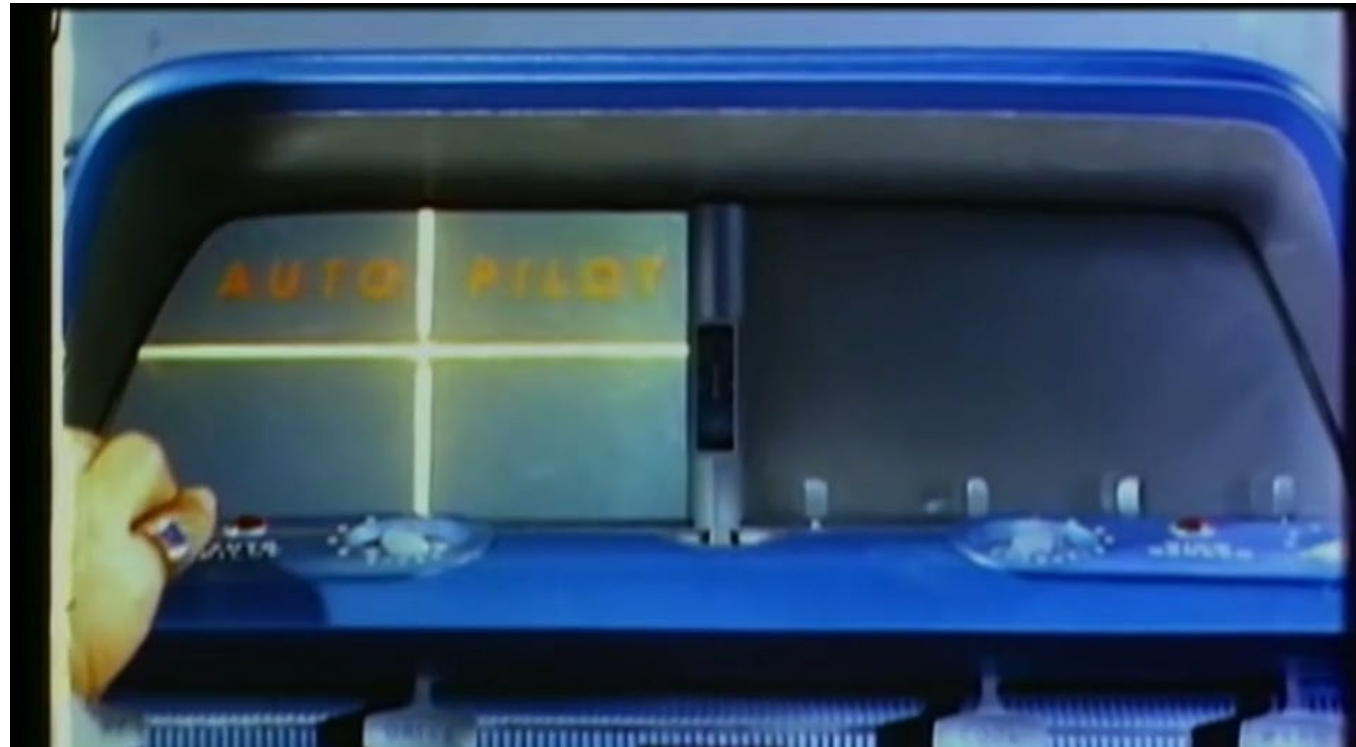
and
50M
non-fatal injuries



Driver error
is a critical factor in
over **90%** of crashes

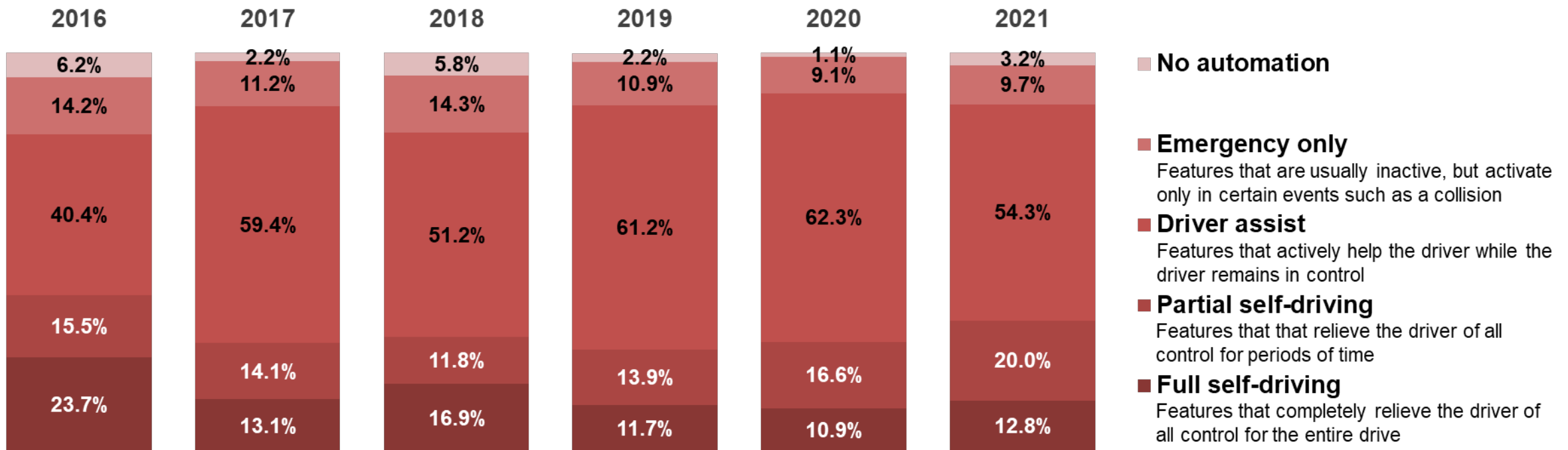
EFFORTS TO AUTOMATE DRIVING ARE NOT NEW

General Motors 1956 Film Highlights Auto Pilot and Systems for Safe Mobility



Source: General Motors 1965 downloaded Dec 6, 2021 from <https://www.youtube.com/watch?v=F2iRDYnzwtk>

Acceptance of Vehicle Automation: Six Year Trends Show Continued Interest in “Assistance”



Note: Percentages shown are unweighted

Lee, C., Gershon, P., Reimer, B., Mehler, B. & Coughlin, C. (2021). Consumer Knowledge and Acceptance of Driving Automation: Changes Over Time and Across Age Groups. Proceedings of the Human Factors and Ergonomics Society Annual Meeting, 65(1), 1395–1399.

Unpublished 2021 MIT AVT Survey Data

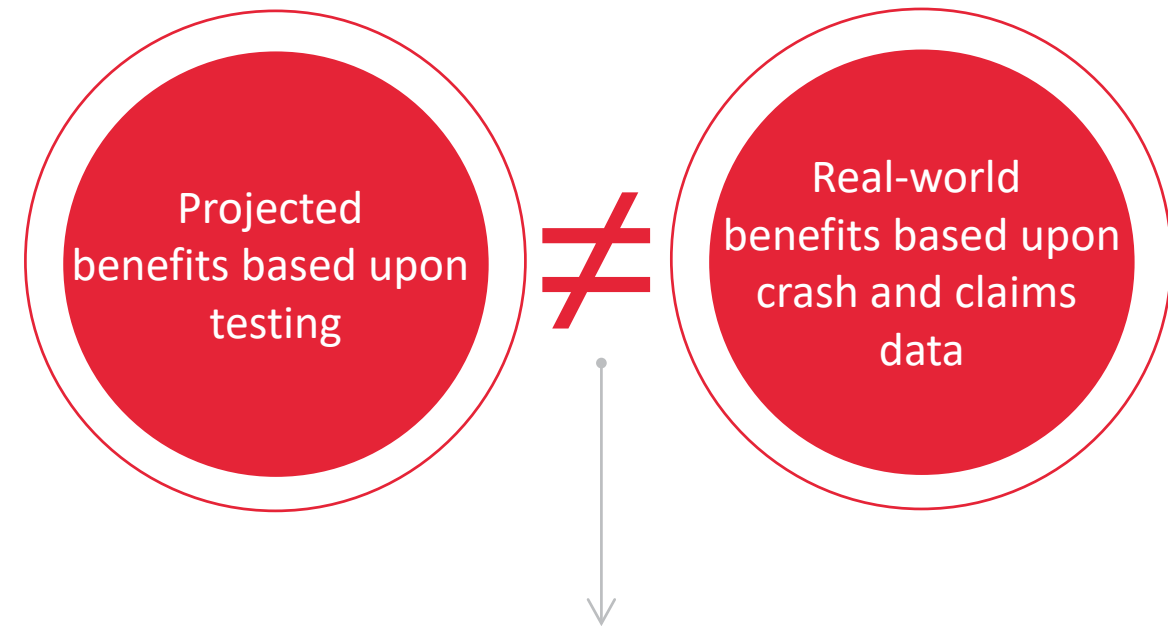
GAP ANALYSIS

The Need for New Data Driven Approaches to Success

Advanced Driver Assistance Systems (ADAS) and Automated Driving Systems (ADS) are predicated on a set of conditional operating characteristics, yet:

- Drivers may not have the understanding and skills necessary to successfully leverage technologies
- Many systems require driver management and oversight
- Technologists often assume ideal performance of both the human and system
- Infrastructure is less than ideal

Past research into ADAS and ADS is limited in scope and context when it comes to understanding how actual consumers interact with such technology.



Why are systems often less effective than projections?

AVT

The Advanced Vehicle Technology Consortium

Originators: MIT AgeLab, Touchstone Evaluations & Agero

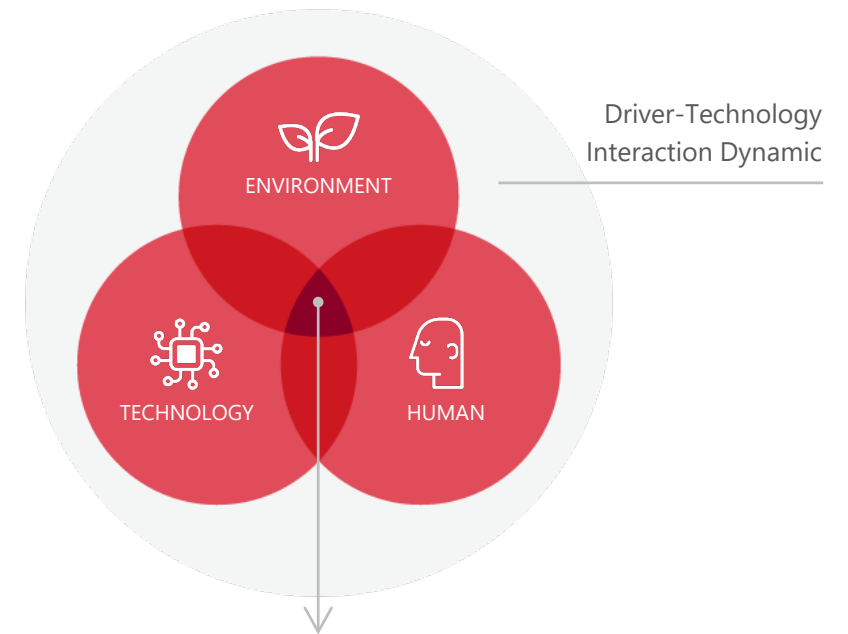
Founding Members: Aptiv, Liberty Mutual, Jaguar Land Rover, Veoneer & Toyota

Current Members*: Agero, Aptiv, Jaguar Land Rover, Veoneer (Arriver), Toyota (TMC, TRI, TIMS), Consumer Reports, Progressive, Insurance Institute for Highway Safety, Google (Waymo), JD Power, Audi (VW, Cariad), Lear, Travelers, Affectiva, The LAB (GIE Stellantis & Groupe Renault), Nissan, Bosch, Autoliv, Seeing Machines, Subaru, Zenseact (Volvo Cars, Polestar), Allstate & Honda

Other Supporters: TravelCenters of America & Santos Family Foundation

Focus: To collect and analyze cutting edge data that objectively characterizes the behavioral and safety benefit of advanced driver assistance systems, higher levels of automation, and other in-vehicle technologies under real-use conditions

Looking Beyond the Technology
Towards Consumer Understanding



To develop: An understanding of system performance and how drivers adapt to, use (or do not use), and behave with advanced vehicle technologies

*member affiliates in parenthesis

Investigating Automated Technology Use in the Wild



Fridman, L., Brown, D., Glazer, M., Angell, W., Dodd, S., Jenik, B., Terwilliger, J., Kindelsberger, J., Ding, L., Seaman, S., Abraham, H., Mehler, A., Sipperley, A., Pettinato, A., Seppelt, B., Angell, L., Mehler, B. & Reimer, B. (2018). MIT Autonomous Vehicle Technology Study: Large-Scale Deep Learning Based Analysis of Driver Behavior and Interaction with Automation. Massachusetts Institute of Technology, Cambridge, MA. <https://arxiv.org/pdf/1711.06976.pdf>

What Is an "Acceptable" Off-Road Glance?



Glance:

On-Road

Glance Length (s):

2.50

Percent Off-Road:

41

Max Off Road Length (s):

1.53

Tesla Autopilot use in a construction zone

Long Off-Road Glances are Increasingly Common



Texting while using Volvo Pilot Assist

Glance:

Off-Road

Glance Length (s):

3.07

Percent Off-Road:

87

Max Off Road Length (s):

3.07

Did Looming Save the Day?

```

--- epoch constants ---
epoch_type: tesla_toc_dis
is_day: 1
vehicle_speed_mph: None
speed_limit_mph: None
toc_vehicle_speed_mph: 62.5
toc_speed_limit_mph: 45

--- important variables ---
autopilot_state: 3
secs_to_toc_dis: -5.0
speed_mph: 66.1
speed_limit_mph: 45

--- other constants ---
autopilot_hands_on_state: 1
autopilot_stalk: 64
acc_enable_speed: 13.6
acc_hold_state: 0
acc_state: 4
steering_control_type: 1
auto_lane_change_state: 7
autopilot_knob: 66
brake_pedal: 0
brake_pedal_state: 0
pedal_pos_percent: 0.0
steering_haptic_request
  
```

Glance:

Off-Road

Glance Length (s):

0.00

Percent Off-Road:

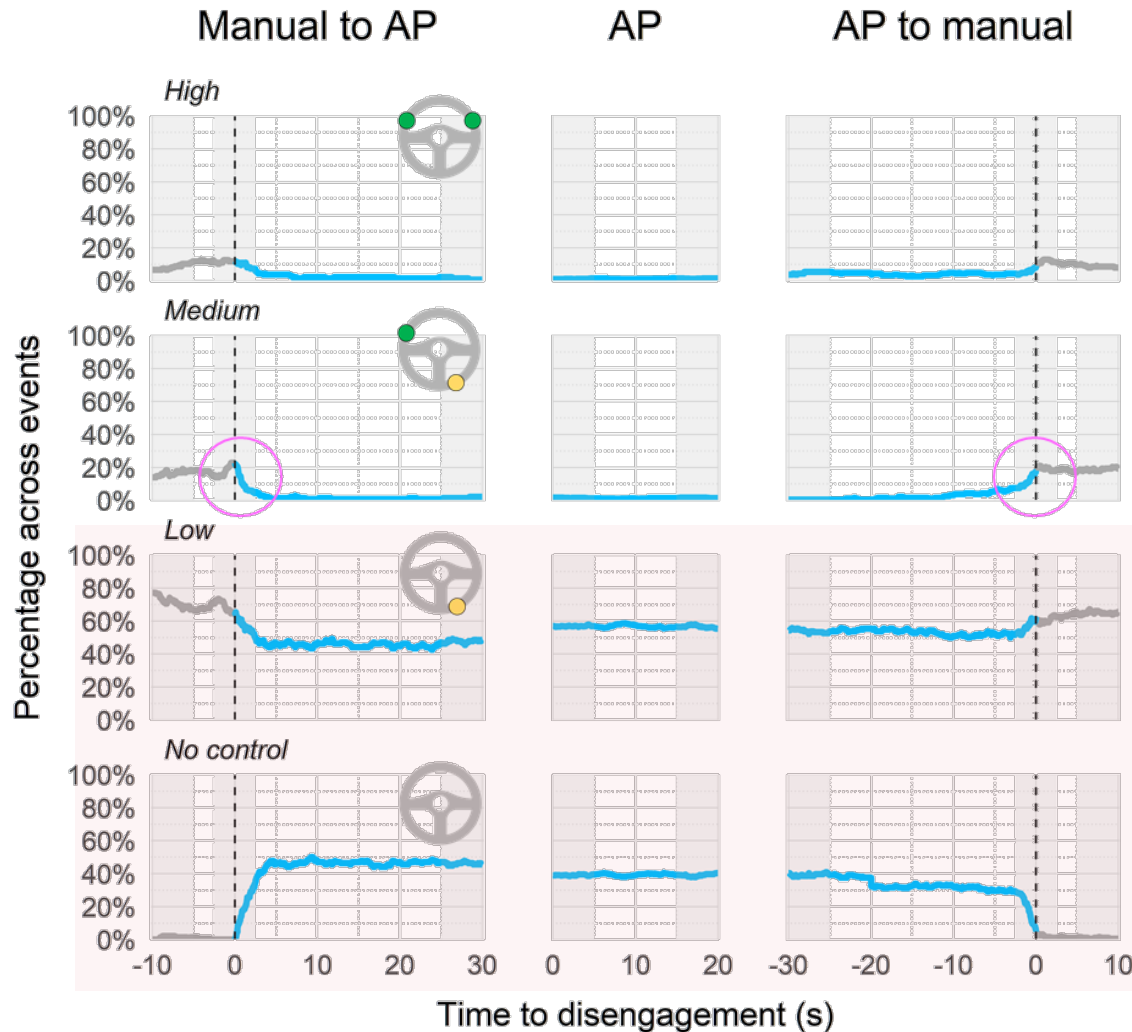
100

Max Off Road Length (s):

0.00

“Out-of-the-loop” behavior while using Autopilot approaching a construction zone

Hands-on-Wheel and Automation Use

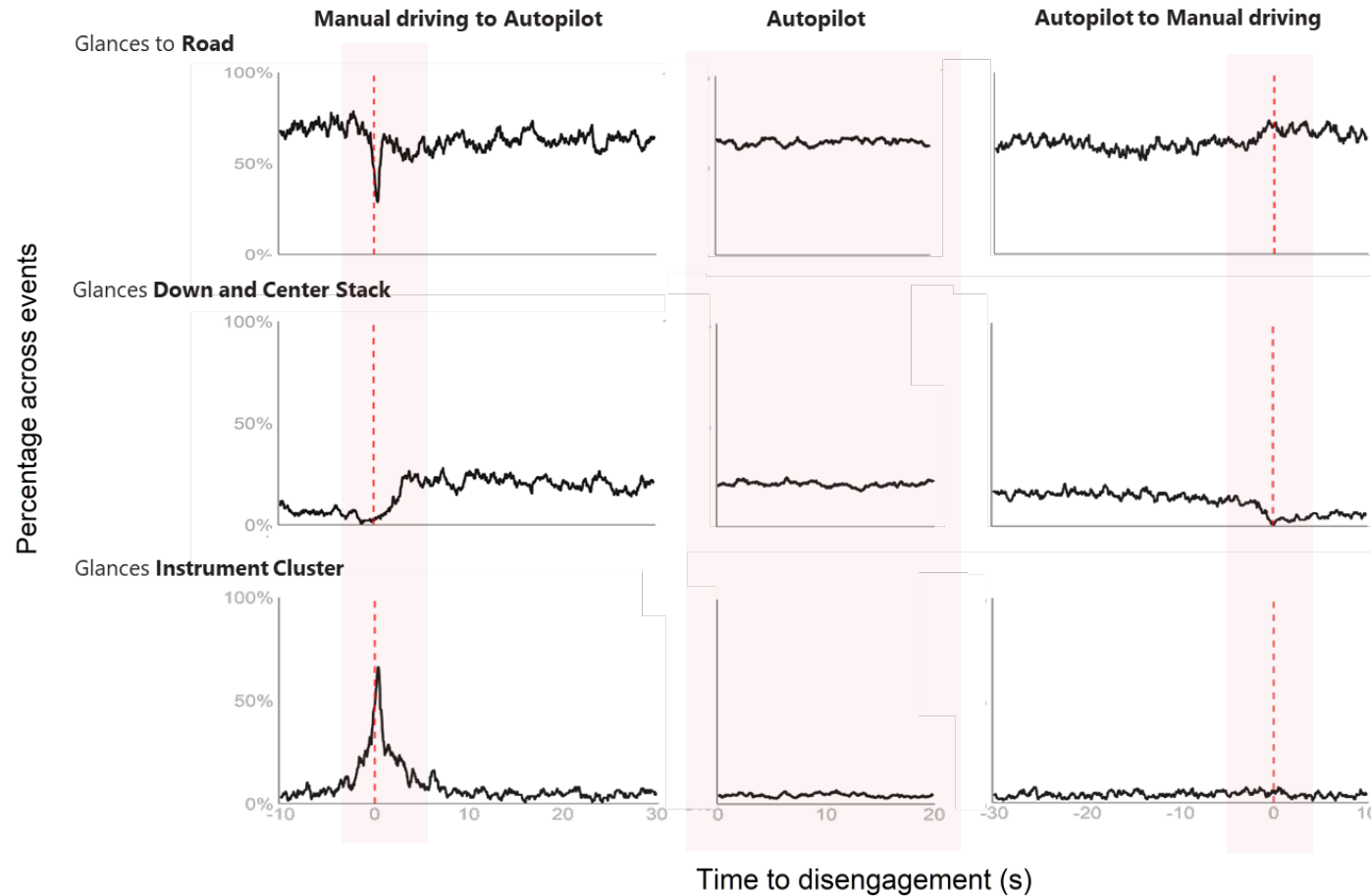


Rapid increase in hands-free driving (no control) from 1% to 46% soon after engagement in AP and throughout AP use.

Low hand placements dominate after AP disengagement.

Morando, A., Gershon, P., Mehler, B. & Reimer, B. (2021). Visual attention and steering wheel control: From engagement to disengagement of Tesla Autopilot. *Proceedings of Proceedings of the 65th Annual Meeting of the Human Factors and Ergonomics Society.*

Visual Attention and Automation Use



The proportion of off-road glances exceeding 2s (historically considered long glances away from the road) during Autopilot use was 22%.

This compares to 4% just after disengagement. Prior work with ACC + Lane Centering found 8 – 11%

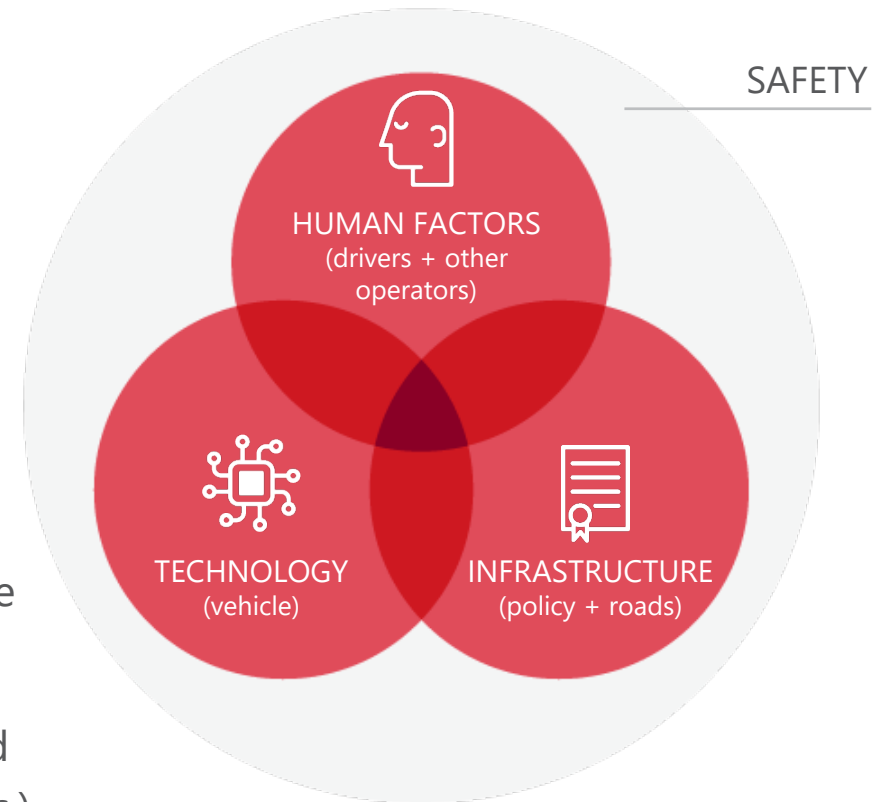
Morando, A., Gershon, P., Mehler, B. & Reimer, B. (2021). Visual attention and steering wheel control: From engagement to disengagement of Tesla Autopilot. *Proceedings of Proceedings of the 65th Annual Meeting of the Human Factors and Ergonomics Society.*

Morando, A., Gershon, P., Mehler, B. & Reimer, B. (2021). A model for naturalistic glance behavior around Tesla Autopilot disengagements. *Accident Analysis and Prevention, 161.*

AI IS A KEY BUILDING BLOCK FOR FUTURE APPLICATIONS, BUT...

We Need a Broader Systems Level View for Safe and Successful Deployment

- Many engineers look to AI as the solution. However, in reality, it is a component of a broader system where the AI (automation) is brittle and requires (except in the narrowest of conditions) human supervision.
- Recent investments in automated driving have hidden costs, nonetheless:
 - Assistive automation (e.g. ADAS, SAE L1 / L2) is poised for market growth
 - Conditional automation (e.g. SAE L3) will be developed, but will have limited impact
 - Higher level automated vehicles (e.g. SAE L4) will continue to evolve slowly
- A systems perspective is often “in view” but slightly “out of focus” when the emphasis is centered on technology alone as a solution
- Unless there is a clear technological breakthrough, we are far from AGI and at great risk of an AI pull back (funding and/or regulatory limits on AVs, etc.)



AI FOR PROTECTION

Driver Monitoring & Support Systems

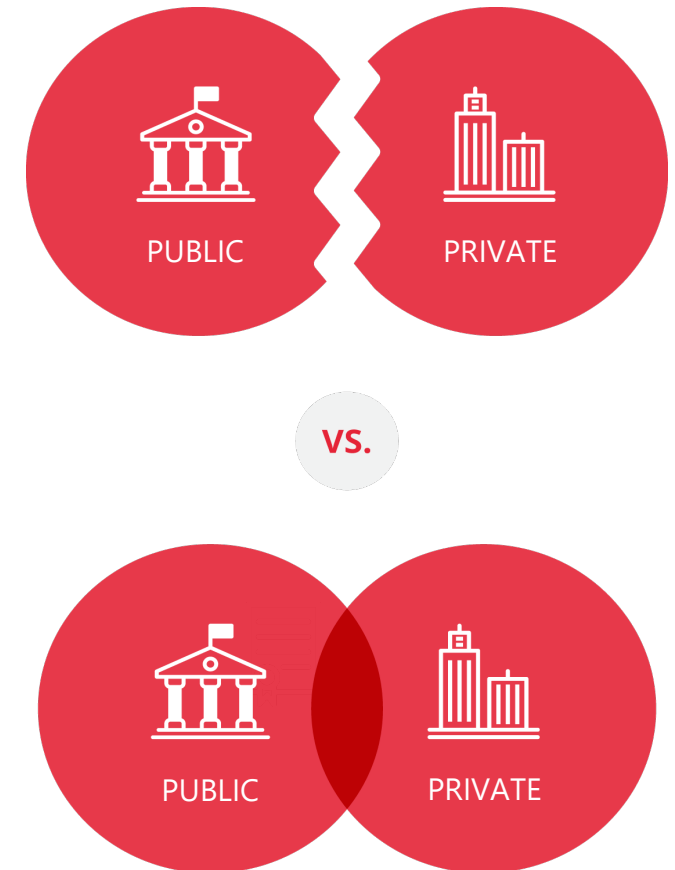
- Driver attention may be at a historic low and there are clear risks that assistive automation may exacerbate this problem.
- Driver monitoring and support can offer benefits under all automation levels, but the impact of production implementations on risk is unknown.
- Increased automation needs to be coupled with increased comfort, convenience, reduced environment impact, and safety, but also requires that systems help support a “driver’s” new role.
 - Monitoring
 - Collaboration
 - Readiness to take-over
- New approaches are needed to monitor, manage and motivate drivers as an integrated component of the automation system.



THE FUTURE MAY BE AUTONOMOUS, BUT...

An Agreement on a Safety Target Is a Key to Success

- Safety targets are life and death decisions that impact a range of costs for suppliers, manufacturers, consumers, and other stakeholders
- Waiting for enhanced safety requirements can minimize benefits useful in mitigating harm today, while ignoring needs risks an erosion of consumer trust and a continued health crisis
- Society needs a common pathway to safer roads with clearer, collaboratively set and communicated goals. Automation offers an opportunity to develop a better system
- Government needs to take an active role, with all parties needing to be willing to collaborate in continual process improvement
- **What is safe enough today will not be tomorrow!**



Reimer, B. (2018). There's more to the safety of driverless cars than AI. TEDx Waltham.



QUESTIONS?

Bryan Reimer, Ph.D.
reimer@mit.edu

